

Explicit method for solving Alfvén
wave in M3D-C1

Matrix assembling and factoring is time consuming

- Currently we use implicit or semi-implicit method to solve MHD equations.
- For nonlinear simulation, this requires recalculating and refactoring the MHD equation matrix at every timestep.
- For Alfvén wave simulation ($\omega^* \tau_A \sim 0.1$), the time step must be small ($\Delta t \sim \tau_A$), leading to long simulation time.

Linear solver avoids assembling but miss nonlinear physics

- We can solve linear MHD equation, whose matrix only depends on equilibrium quantities (B_0 , p_0) and is fixed.
- The Alfvén mode will still be saturated at a small level ($\delta B/B \sim 0.001$) because of particle nonlinearity.
- Mode-mode coupling will be missing in the simulation.

Treat nonlinear terms explicitly

- To include the nonlinear MHD effect, we can treat the nonlinear MHD terms as explicit terms on the right-hand-side of equations.

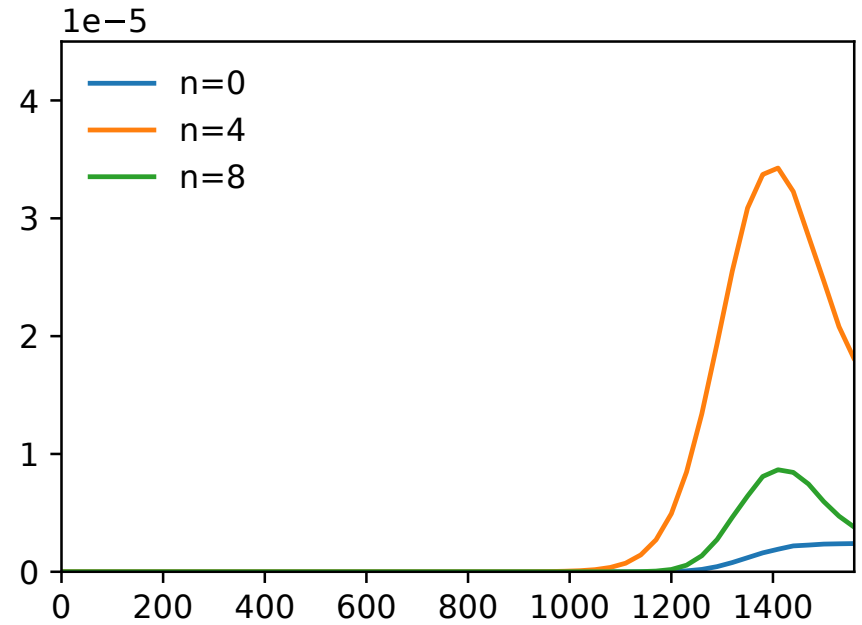
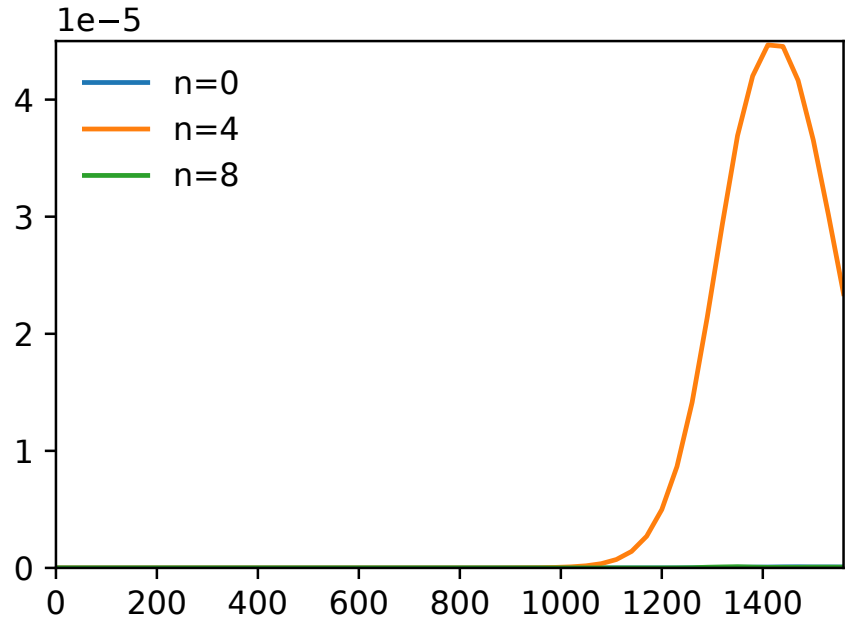
$$SX_{n+1} = DX_n + \mathbf{b}$$

- The matrices S, D are unchanged and only need to be factorized once.
- The nonlinear terms only needs to be calculated as a vector instead of matrix. The time complexity is $O(\text{dofs} \cdot \text{pts})$ instead of $O(\text{dofs} \cdot \text{dofs} \cdot \text{pts})$.
- The CFL condition will be determined by δv , δB and not by v_A , B_0
 - To avoid numerical instability, we can use a smaller timestep ($\sim 0.2 \tau_A$) and subcycles.

Computation time comparison

- Implicit method
 - 70s (matrix assembling) + 15s (solver)
- Explicit method
 - [1.5s (nonlinear vector calculation) + 1.5s (solver)]
*5

Results



Acceleration using GPU?

- Calculation of nonlinear vector can be accelerated using GPU.
- I wonder if there is a good way to accelerate the solving of a factorized matrix using GPU.